

Constant Coefficient Linear systems

Consider the following system of ODEs.

$$y_1' = y_1 + 2y_2 \quad \text{————— (1)}$$

$$y_2' = 3y_1 + 2y_2$$

$$\text{Let } \vec{y}(t) = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}, \quad \vec{y}'(t) = \begin{pmatrix} y_1' \\ y_2' \end{pmatrix}$$

We can write (1) as

$$\vec{y}'(t) = A \vec{y}(t) \quad \text{————— (2)}$$

$$\text{where } A = \begin{pmatrix} 1 & 2 \\ 3 & 2 \end{pmatrix}$$

Ques: How can we solve this system for $\vec{y}(t)$?

Let us consider the scalar ODE,

$$\frac{dy}{dt} = \lambda y(t), \quad \lambda \text{ ——— (3) growth rate}$$

The solution of this equation is

$$y(t) = C e^{\lambda t}$$

Observe that (2) and (3) are first order linear ^{equation}. We expect their solutions to have a similar form.

Take

$$\vec{Y}(t) = C e^{\lambda t} \vec{v} \quad \text{--- (4)}$$

where λ is a scalar (growth rate)

C - constant

\vec{v} - constant vector

put the solution in (4) into the system

$$\vec{Y}'(t) = A \vec{Y}(t)$$

$$\cancel{\lambda C e^{\lambda t}} \vec{v} = A \cancel{C e^{\lambda t}} \vec{v}$$

$$\lambda \vec{v} = A \vec{v}$$

$$\boxed{A \vec{v} = \lambda \vec{v}} \quad (\text{eigenvalue problem})$$

This implies that λ is an eigenvalue of A with corresponding eigenvector \vec{v} .

$$A\vec{v} = \lambda\vec{v}$$

$$\Rightarrow A\vec{v} - \lambda\vec{v} = \vec{0}$$

$$(A - \lambda I)\vec{v} = \vec{0}$$

vector

(system of algebraic equations)

We seek a non trivial \vec{v} (ie $\vec{v} \neq \vec{0}$) that satisfies this equation.

$$\Rightarrow \det(A - \lambda I) = 0 \quad \text{must hold.}$$

\therefore To get the eigenvalue of a matrix A , we solve

$$\det(A - \lambda I) = 0$$

or $|A - \lambda I| = 0$

(characteristic equation)

And for the corresponding eigenvector,
we solve

$$(A - \lambda I) \vec{v} = \vec{0}$$

Thus, $\vec{y}(t) = c e^{\lambda t} \vec{v}$

is a solution of the system.

If $\vec{y}_1(t) = c_1 e^{\lambda_1 t} \vec{v}_1$ and
 $\vec{y}_2(t) = c_2 e^{\lambda_2 t} \vec{v}_2$, ~~then~~ are solutions

~~$\vec{y}_1(t) + \vec{y}_2$~~ of a linear system, then

$$\vec{y}_1(t) + \vec{y}_2(t) = c_1 e^{\lambda_1 t} \vec{v}_1 + c_2 e^{\lambda_2 t} \vec{v}_2$$

is also a solution of the system.

This is called principle of superposition.

Let us return to the example

$$\vec{y}'(t) = A\vec{y}(t)$$

where

$$A = \begin{pmatrix} 1 & 2 \\ 3 & 2 \end{pmatrix}$$

Let λ be an eigenvalue of A ,

then $|A - \lambda I| = 0$

$$\left| \begin{pmatrix} 1 & 2 \\ 3 & 2 \end{pmatrix} - \lambda \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right| = 0$$

$$\begin{vmatrix} 1-\lambda & 2 \\ 3 & 2-\lambda \end{vmatrix} = 0$$

$$(1-\lambda)(2-\lambda) - 6 = 0$$

$$\lambda^2 - 3\lambda - 4 = 0$$

$$\lambda_1 = 4 \quad \text{or} \quad \lambda_2 = -1$$