

# Math215/255 Midterm 1 P

Name:.....Solution..... Student Number:.....

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## Question 1

(5 points) Solve the following initial value problems for  $y(t)$ :  $ty' + 2y = \cos(t)$ ,  $y(\pi) = 0$ .

$$y' + \frac{2}{t}y = \frac{1}{t}\cos(t)$$

integrating factor is  $h(t) = e^{\int \frac{2}{t} dt} = t^2$

$$\frac{d}{dt}(t^2 y) = t \cos(t)$$

integrating,  $t^2 y = t \sin(t) + \cos(t) + c_1$

$$y(t) = \frac{1}{t} \sin(t) + \frac{1}{t^2} \cos(t) + \frac{c}{t^2},$$

$$y(\pi) = 0 \implies c = 1$$

$$y(t) = \frac{1}{t} \sin(t) + \frac{1}{t^2} \cos(t) + \frac{1}{t^2}.$$

## Question 2

(10 points) Consider the following system of first order ODEs

$$\begin{aligned}\frac{dy_1}{dt} &= 2y_1(t) - 2y_2(t) \\ \frac{dy_2}{dt} &= 2y_1(t) + 2y_2(t)\end{aligned}$$

(a) Find the general solution of the system. Convert any complex exponentials in your solutions into “real forms” involving sines and cosines.

$$\text{Let } A = \begin{pmatrix} 2 & -2 \\ 2 & 2 \end{pmatrix}$$

For the eigenvalues,  $\lambda^2 - 4\lambda + 8 = 0$  and this gives  $\lambda_1 = 2 + 2i$  and  $\lambda_2 = 2 - 2i$ .

For the eigenvector  $\vec{v}_1$ ,

$$\begin{pmatrix} -2i & -2 \\ 2 & -2i \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \implies \vec{v}_1 = \begin{pmatrix} i \\ 1 \end{pmatrix}$$

For the eigenvector  $\vec{v}_2$ ,

$$\begin{pmatrix} 2i & -2 \\ 2 & 2i \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \implies \vec{v}_2 = \begin{pmatrix} -i \\ 1 \end{pmatrix}$$

We know that the general solution of the system is given by

$$\vec{y}(t) = \text{Re} \left( \begin{pmatrix} i \\ 1 \end{pmatrix} e^{(2+2i)t} \right) + \text{Im} \left( \begin{pmatrix} i \\ 1 \end{pmatrix} e^{(2+2i)t} \right)$$

Consider

$$\left( \begin{pmatrix} i \\ 1 \end{pmatrix} e^{(2+2i)t} \right) = e^{2t} \begin{pmatrix} i \\ 1 \end{pmatrix} (\cos(2t) + i \sin(2t)) = e^{2t} \begin{pmatrix} -\sin(2t) \\ \cos(2t) \end{pmatrix} + i e^{2t} \begin{pmatrix} \cos(2t) \\ \sin(2t) \end{pmatrix}$$

Therefore, the general solution is

$$\vec{y}(t) = c_1 e^{2t} \begin{pmatrix} -\sin(2t) \\ \cos(2t) \end{pmatrix} + c_2 e^{2t} \begin{pmatrix} \cos(2t) \\ \sin(2t) \end{pmatrix}$$

(b) Use the initial conditions  $y_1(0) = 1$  and  $y_2(0) = 2$  to find the constants in your solution.

$$\begin{pmatrix} 1 \\ 2 \end{pmatrix} = c_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 0 \end{pmatrix} \implies c_1 = 2, \quad c_2 = 1.$$

Therefore,

$$\vec{y}(t) = 2 e^{2t} \begin{pmatrix} -\sin(2t) \\ \cos(2t) \end{pmatrix} + e^{2t} \begin{pmatrix} \cos(2t) \\ \sin(2t) \end{pmatrix}$$

### Question 3

(7 points) Determine the value of  $k$  for which the following equation is exact

$$(y \cos(x) + kxe^y) dx + (\sin(x) + x^2e^y - 1) dy = 0.$$

For this equation to be exact, we need  $M_y = N_x$ .

$$M(x, y) = y \cos(x) + kxe^y \implies M_y(x, y) = \cos(x) + ke^y$$

$$N(x, y) = \sin(x) + x^2e^y - 1 \implies N_x(x, y) = \cos(x) + 2xe^y$$

Comparing  $M_y$  and  $N_x$ , we have that  $k = 2$ .

Therefore, the equation is

$$(y \cos(x) + 2xe^y) dx + (\sin(x) + x^2e^y - 1) dy = 0,$$

Let  $\Phi(x, y) = C$  be the general solution of this equation. Then

$$\frac{\partial \Phi}{\partial x} = M(x, y) = y \cos(x) + 2xe^y \implies \Phi(x, y) = y \sin(x) + x^2e^y + \gamma_1(y)$$

$$\frac{\partial \Phi}{\partial y} = N(x, y) = \sin(x) + x^2e^y - 1 \implies \Phi(x, y) = y \sin(x) + x^2e^y - y + \gamma_2(x)$$

Comparing the two  $\Phi(x, y)$  functions, we have that  $\gamma_1(y) = y$  and  $\gamma_2(x) = 0$ .

Therefore, the general solution is

$$y \sin(x) + x^2e^y - y = C$$

Applying the initial condition  $y(\pi) = 0$ , we have  $C = \pi^2$ .

$$y \sin(x) + x^2e^y - y = \pi^2.$$

### Question 4

(i) C

(ii)  $\vec{y}(t) \rightarrow \begin{pmatrix} 0 \\ 0 \end{pmatrix}$  as  $t \rightarrow \infty$

(iii) B

## Question 5

(12 points) Consider the following ODE

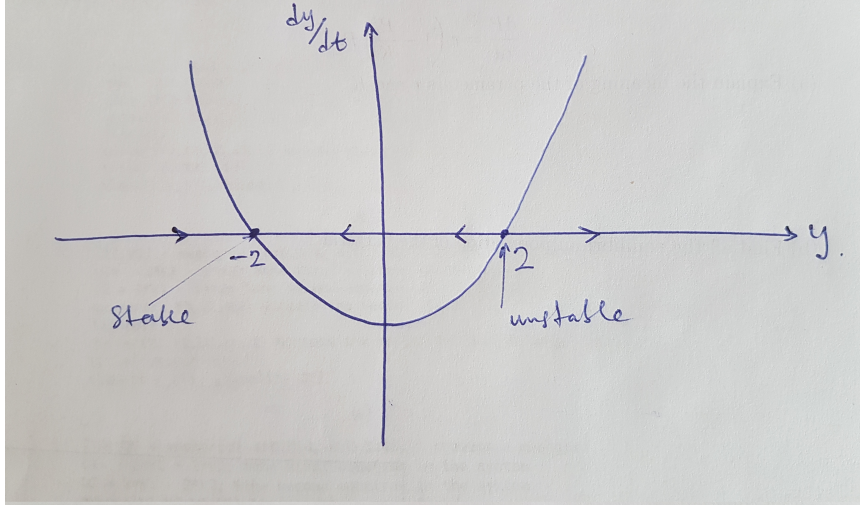
$$\frac{dy}{dt} = \lambda(y^2 - 4), \quad \text{where } \lambda > 0.$$

(a) Find all the equilibria (steady state solutions) of the differential equation. For steady state solutions, we set  $\frac{dy}{dt} = 0$  and solve for  $y$  in

$$\lambda(y^2 - 4) = 0,$$

which gives  $y = -2$  and  $y = 2$ .

(b) Sketch the graph of  $\frac{dy}{dt}$  vs  $y(t)$  and use it to determine which of these equilibria is stable, unstable, or semi-stable.



(c) Use the initial condition  $y(0) = 1$  to find a solution to the equation.

Hint: You may need the partial fraction  $\frac{1}{(y-a)(y-b)} = \frac{A}{(y-a)} + \frac{B}{(y-b)}$ .

$$\begin{aligned} \frac{dy}{dt} &= \lambda(y^2 - 4), \\ \implies \frac{dy}{(y-2)(y+2)} &= \lambda dt \\ \frac{1}{(y-2)(y+2)} &= \frac{A}{(y-2)} + \frac{B}{(y+2)} \quad \implies \quad A = \frac{1}{4}, \quad B = -\frac{1}{4} \end{aligned}$$

Therefore, we have

$$\begin{aligned} \int \left( \frac{1}{4} \frac{1}{(y-2)} - \frac{1}{4} \frac{1}{(y+2)} \right) dP &= \lambda t + c_1, \\ \frac{1}{4} \ln(y-2) - \frac{1}{4} \ln(y+2) &= \lambda t + c_1, \\ \frac{(y-2)}{(y+2)} &= c_2 e^{4\lambda t}, \quad (c_2 = e^{4\lambda t}) \\ y(t) &= \frac{2 + 2c_2 e^{4\lambda t}}{1 - c_2 e^{4\lambda t}} \end{aligned}$$

Applying the initial condition  $y(0) = -1$ , we have  $c_2 = -3$ .

$$y(t) = \frac{2 - 6e^{4\lambda t}}{1 + 3e^{4\lambda t}}.$$

(d) Find the limit of this solution  $y(t)$  as  $t \rightarrow \infty$ .

$$\lim_{t \rightarrow \infty} y(t) = \frac{2 - 6e^{4\lambda t}}{1 + 3e^{4\lambda t}} = -2.$$